

2D Mass Mapping

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•Mass Mapping: 2D-MASS-WL, 3D-MASS-WL

- Originally, mass maps were considered not scientifically useful, but the situation is now clearly different.
- The field is evolving, and several 2D and 3D codes now exist.
- Science case work ongoing, and most requirements are not defined





Clusters

 $\hat{\kappa} = P_1 \hat{\gamma}_1 + P_2 \hat{\gamma}_2$

 $P_1(k) = \frac{k_1^2 - k_2^2}{k^2}$ $P_2(k) = \frac{2k_1k_2}{k^2}$

=> PROBLEMS: Noise + Irregular Sampling



Mass mapping as an inverse problem

Binned data: $\gamma = F^* P F \kappa$

Unbinned data: $\gamma = T^* PF\kappa$

T = Non Equispaced Discrete Fourier Transform (NDFT)

$$\min_{\kappa} \frac{1}{2} \parallel \gamma - \mathbf{P}\kappa \parallel_2^2 \quad \text{with} \quad \mathbf{P} = T^* PF$$

$$g = \frac{\gamma}{1 - \kappa} \longrightarrow \qquad \min_{\kappa} \frac{1}{2} \parallel (1 - \kappa)g - \mathbf{P}\kappa \parallel_{2}^{2}$$

 $L = \mathbf{T}^* \mathbf{P} \mathbf{F}$ is not directly invertible \Rightarrow Linear inverse problem.





Linear Methods:

•Kaiser-Squires (1993) + Gaussian smoothing

Non Linear methods:

• For clusters:

•Model fitting algorithms (Bartelmann et al, 1996; Bradac et al, 2005; Jullo and Kneib, 2009).

•Aperture Mass (Seitz and Schneider, 1996; 2002)

• For larger fields:

•Maximum Likehood (Bartelmann et al, 1996)

•MemLens (Bridle et al, 1998; Marshal and Hobson, 2002)

•FastLens + MR-Lens (Starck, Pires, Refregier, 2006; Pires et al, 2009)

•Glimpse2D (Lanusse, Starck, Leonard, Pires, in preparation).





Aperture Mass and Wavelets

$$M_{ap}(\boldsymbol{\theta}) = \int d^2 \boldsymbol{\vartheta} \ \gamma_t(\boldsymbol{\vartheta}) Q(|\boldsymbol{\vartheta}|)$$

$$M_{ap}(\theta) = (\mathbf{\Phi}^t \kappa)_{\theta}$$



⇒ Wavelets filters are formally **indentical** to Mass aperture

A. Leonard, S. Pires, J.-L. Starck, "Fast Calculation of the Weak Lensing Aperture Mass Statistic", MNRAS, 423, pp 3405-3412, 2012.







=> Write the mass-mapping as a single optimization problem with a *multi-scale sparsity prior* addressing all these issues (i.e. reduced shear, missing data, noise).





The 2D Glimpse Algorithm

$$\min_{\kappa} \frac{1}{2} F(\kappa) + \lambda \parallel \Phi^t \kappa \parallel_1 \quad \text{with} \quad F(\kappa) = \frac{1}{2} \parallel (1 - \kappa)g - \mathbf{P}\kappa \parallel_2^2$$

Primal-dual splitting:

$$\begin{cases} \kappa^{(n+1)} = \kappa^{(n)} + \tau \left(\nabla F(\kappa^{(n)}) + \mathbf{\Phi} \alpha^{(n)} \right) \\ \alpha^{(n+1)} = \left(\mathrm{Id} - \mathrm{ST}_{\lambda} \right) \left(\alpha^{(n+1)} + \mathbf{\Phi}^{t} (2\kappa^{(n+1)} - \kappa^{(n)}) \right) \end{cases}$$

adapted from Vu (2013)

- Fast and flexible algorithm
- Sparsity constraint λ estimated locally by noise simulations \implies Accounts for survey geometry, varying noise levels



Missing Data + Noise



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Flexion

Shear is noise dominated on small scales ==> Substructures are lost

Small-scale substructure can be recovered from strong lensing when available.

Gravitational Flexion is useful in the intermediate regime.

Flexion gives information relative to the third order derivatives of the lensing potential







Shear (left) and first flexion (right) (Bartelmann 2010)

 $\mathcal{F} = \nabla \kappa$



Shear and Flexion Noise Power Spectrum







Flexion Information

We can integrate flexion in our reconstruction framework

=> Jointly fit shear and flexion

$$\min_{\kappa} \frac{1}{2} \parallel (1-\kappa) \begin{bmatrix} g \\ F \end{bmatrix} - \begin{bmatrix} \mathbf{P} \\ \mathbf{Q} \end{bmatrix} \kappa \parallel_2^2 + \lambda \parallel \mathbf{\Phi}^t \kappa \parallel_1$$

=> Jointly fit shear and flexion with redshift information

$$\begin{split} \min_{\kappa} \frac{1}{2} \parallel (1 - \mathbf{Z}\kappa) \begin{bmatrix} g \\ F \end{bmatrix} - \mathbf{Z} \begin{bmatrix} \mathbf{P} \\ \mathbf{Q} \end{bmatrix} \kappa \parallel_{2}^{2} + \lambda \parallel \mathbf{\Phi}^{t}\kappa \parallel_{1} \\ \end{split}$$
with $\mathbf{Z} = \sum_{critic}^{\infty} / \sum_{critic} (z_{i})$

$$\sum_{crit}^{\infty} = \lim_{z \to \infty} \sum_{crit} (z) \\ \sum_{crit} (z_{s}) = \frac{c^{2}}{4\pi G} \frac{D_{S}}{D_{L} D_{LS}} \end{split}$$

Individ

•Directly map the surface mass density of the lens

•Mitigate the mass-sheet degeneracy when κ becomes significant (Bradac et al. 2004)



Simulations with Flexion

Simulate reduced flexion

Flexion noise $\sigma_F = 0.029 \operatorname{arcsec}^{-1}$ (Cain et al, 2011)



Reconstruction from one realisation

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Flexion



Benefits of adding flexion:

- Improvement on the recovered profiles below 0.5 arcmin
- Recovery of small-scale substructure at the 10 arcsec scale

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Conclusions

* **GLIMPSE2D**: A new mass mapping algorithm, based on sparsity and proximal optimization theory:

- Does not require angular binning of the ellipticities
- Accounts for reduced shear
- Proper regularization of missing data

A new framework :

- => Can include individual redshift PDFs of sources
 - •Directly map the surface mass density of the lens
 - •Mitigate the mass-sheet degeneracy when the convergence becomes significant (Bradac et al. 2004)
- => Can include flexion measurements if available
- ⇒ Can be also be used for non-parametric high-resolution cluster density mapping from weak lensing alone

Lanusse F., Starck J.-L., Leonard A., and Pires S. (2015), High Resolution Weak Lensing Mass Mapping combining Shear and Flexion, in prep.

- Bridge between low resolution weak lensing and high resolution strong lensing
- Can recover cluster substructures without strong lensing information
- Ideal tool for investigating models of dark matter

* The science case is not yet mature: no requirement.

